



# Different mechanisms and scenarios for the local RF power production switching in a case of single CLIC PETS or accelerating structure failure.

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Ranking 1: R&D needed for feasibility demonstration of the machine

The objective of these R&D items is to show that the key machine parameters are not unrealistic. In particular, a proof of existence of the basic critical constituents of the machines should be available upon completion of the Ranking 1 R&D items.

### Reliability

 In the present CLIC design, an entire drive beam section must be turned off on any fault (in particular on any cavity fault). <u>CLIC needs to develop a mechanism</u> to turn off only a few structures in the event of a fault. At the time of writing this report, there is no specific R&D program aimed at that objective but possible schemes are being studied.



#### CLIC 30 GHz RF structures





Power extracted ~560 MW×130 ns Max. surface electric field ~ **110 MV/m** (due-to-slots enchantment included) Input Power ~ 130 MW×130 ns Max. surface electric field ~ **350 MV/m** 











Artistic view of the novel high RF power splitter.









Fields plot in choke junction. Circular waveguide, mode H11





Distance, mm

Max. surface field is 75% of that in a standard rectangular waveguide



Rotation of two consequent "polarizers" is resulted in additional phase advance due to effective change of electrical length for the different polarizations. Tuning range can be increased with a simple lengthening of the elliptical part of the device





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RF power budget of the splitter vs. Rotation angle. 60

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output RF phase.





CLIC accelerator unit layout with local termination of the RF power <u>delivery</u>







CLIC accelerator unit layout with local termination of the RF power <u>generation</u>



- #1. We know that serious breakdown "eats" practically all RF power.
- #2. With re-circulation the output/input power has periodical beating.
- #3. Strong fields at the input of PETS are induced.
- #4. Two PETS couplers per one power station are needed.



#1,2. High power RF splitter and 2 PETS de-phasing



CLIC accelerator unit layout with local termination of the RF power generation



- #1. Two power stations should be sacrificed in a case of any single breakdown.
- #2. Upstream PETS is needed no measure to cancel breakdown in #1 PETS.
- #3. Strong fields at the input of downstream PETS are induced.
- #4. Two PETS couplers per one power station.





CLIC accelerator unit layout with local termination of the RF power <u>generation</u>



- #1. Three PETS couplers per one power station plus dedicated variable RF phase shifters ( -> inefficiency and complication).
  #2. Upstream half-part of PETS is not protected.
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#### RF breakdown



- #1. Alignment (on/off)?
- #2. Choke in over-moded waveguide. By itself it could be the place where the breakdown is most likely probable. Mode conversion and transverse kick danger.
- #3. Low frequency trapped modes in a beam pipe (need to be damped?)



PETS power production modeling



RF power profiles along PETS

0.4

Distance, m

Power "ON"

Power "OFF"

0.6

0.8







0.2

Power, norm.

0.75

0.5

0.25

0

0



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#4. Single PETS RF properties modification

31



Modified PETS geometry with a pull/push option.



+3mm

0.9

2

Radius increase, mm

3

4

+4mm



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## Summary

- #1. Even the accelerating structure failure looks more probable, we can not ignore the chances of PETS RF breakdown.
- #2. Following the few preliminary discussions and my personal opinion the best candidate will be "4-knives" PETS option.
- #3. The detailed study of "8-petal" PETS to complete technical design for the damping slots and new loads configuration should be done (already started).
- #4. The developed RF power attenuator and RF phase shifter by themselves are very useful components that can be used even in CTF#3 30 GHz high power operation.