CTF3 machine protection system (CTF3 MPS)

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General facts

MPS protects CTF machine against the consequences coming from 'bad' transfer of the particles from CTF3 linac source to CLEX/intermediate dumps/spectrometer lines.

In case of 'bad' transmission MPS affects beam production to fall on a safe situation

MPS must be very fast, autonomous and as independent as possible of the control and timing system

MPS does not protect humans

Bad transfer (1)

Small repetitive losses < 10 - 20%

- ñ They don't damage the hardware
- $\tilde{\mathsf{n}}$ They raise personnel radiation hazard

Action taken:

 $\tilde{\mathsf{n}}$ MPS should either decrease beam production or stop the beam in order to lessen radiation

Bad transfer (2)

Fraction of beam pulse lost locally

 \tilde{n} damages the hardware

Action taken:

- ñ MPS stops the LINAC source beam production inside the present pulse
- ñ Apply recovery procedures

Note – definition of beam loss

n Beam loss is given by difference of beam charge measured at two consecutive sensors (WCMs)

Proposed solution (1)



Proposed solution (2)



In the first stage only 2 WCMs are installed Basic part of the system + infrastructure is built to test the speed of the system

Infrastructure



Speed

Some facts about the speed of the system:

- \tilde{n} WCM time to react $t_{PD1} = 8ns$
- \tilde{n} substractor electronic delay measured to be $t_{PD2} = 16ns^*$
- ñ FLEXWELL cable from WCM1 to substractor t_{PD3} =43ns^{**}
- ñ FLEXWELL cable from WCM2 to substractor $t_{PD4}=10ns^{**}$
- ñ FLEXWELL cable from substractor to E/O t_{PD5} =125ns^{**}
- \tilde{n} electrical/optical conversion + ~4m of the cable $t_{pD6} = 50 ns^{**}$

Delay from WCM2 to GUN: t_{PD_GUN} =8ns+16ns+10ns+125ns+50ns=209ns -> delay from beam passing WCM2 to stop the gun This gives us the minimum reaction time to stop the gun: t_{react} =66ns***+209ns=275ns

^{*} from crossing of the threshold to ECL signal output

^{**} estimated parameter

^{*** 66}ns is the ToL from Linac source to WCM2 in the distance of 20m

Conclusion

In the near future first stage of the system will be installed. This stage is focused on:

- $\tilde{\mathsf{n}}$ make a basic functionality of the system, 2 WCMs are used
- \tilde{n} study of the behavior of the machine (noise, offsets...)
- $\tilde{\mathsf{n}}$ study/selection of the best control system

There is not a lot of possibilities to improve speed of the system (the longest cables will be around 80m!) for distant WCMs is difficult to react within the current pulse