Main Linac Design and Alignment

D. Schulte

Lots of contributions from G. Riddone, H. Mainaud-Durand and A. Latina

### Introduction

- The main linac is an important driver of the structure design
  - the wakefields can render the beam instable
  - they introduce energy spread
- The linac beam dynamics limits the bunch charge and beam current and consequently the efficieny and the luminosity
- Challenges for the linac design are to
  - ensure beam stability
  - limit emittance growth
- Will introduce lattice design for new CLIC parameters (not finished)
  - structure design from A. Grudiev
- Currently want to verify that there is a solution
  - next step will be to find best solution

### Low Emittance Transport Challenges

• Static imperfections

errors of reference line, elements to reference line, elements...

excellent pre-alignment, lattice design, beam-based alignment, beambased tuning

• Dynamic imperfections

element jitter, RF jitter, ground motion, beam jitter, electronic noise, . . .

lattice design, BNS damping, component stabilisation, feedback, retuning, re-alignment

- Combination of dynamic and static imperfections can be severe
- Lattice design needs to balance dynamic and static effects

## Lattice Design Considerations

- Linac lattice is a trade-off
- strong focusing
  - small sensitivity to wakefields
  - dispersive effects important
- large energy spread
  - beam is more stable
  - dispersive effects are increased
- First need to consider beam stability
   ⇒ look at allowed energy spread

- weak focusing
  - high sensitivity to wakefields
  - dispersive effects smaller
- small energy spread
  - beam is less stable
  - dispersive effects are reduced

# Beam Stability

- Transverse wakes act as defocusing force on tail
  - $\Rightarrow$  beam jitter is exponentially amplified
- BNS damping prevents this growth
  - manipulate RF
     phases to have
     energy spread
  - take spread out at end





### **Emittance** Preservation

- $\epsilon_x \gg \epsilon_y \Rightarrow$  consider only  $\epsilon_y$
- Current main linac target:  $\Delta \epsilon_y \leq 5 \,\mathrm{nm}$ 
  - inital  $\epsilon_y \leq 5 \,\mathrm{nm}$
  - may need review to allow for large growth in RTML
- Budget is shared with other effects

 $\Rightarrow$  assume  $2.5\,\mathrm{nm}$ 

Large spread in emittance growth as function of initial distribution

 $\Rightarrow$  need to define probability level (we require 90%)

- Emittance growth is dominated by wakefields
  - even dispersive growth since BNS damping is used

$$\Delta \epsilon_y \propto (W_\perp N \sigma_z \Delta y)^2$$

- $W_{\perp}$  large a (iris radius)
- N- trivial, but  $\eta\propto N$
- $\sigma_z$  large a, small N

### Beam Loading and Bunch Length

- Aim for shortest possible bunch (wakefields)
- Energy spread into the beam delivery system should be limited to about 1% full width or 0.35% rms
- Multi-bunch beam loading compensated by RF
- Single bunch longitudinal wakefield needs to be compensated
  - $\Rightarrow$  accelerate off-crest



- $\bullet$  Limit around average  $\Delta\Phi \leq 12^\circ$ 
  - $\Rightarrow \sigma_z = 65 \,\mu\mathrm{m}$  for  $N = 5.2 \times 10$

# Energy Spread

- Three regions
  - generate
  - maintain
  - compress
- Configurations are named according to RF phase in section 2
- Trade-off in fixed lattice
  - large energy spread is more stable
  - small energy spread is better for alignment



### Lattice Design Strategy

- Chose a strength that ensures beam stability (same as in old lattice)
- At higher energies beam is less sensitive to wakefields
  - $\Rightarrow$  increase beta-function along machine

 $\beta \propto \sqrt{E}, \ \Delta \phi = \text{const}$ 

- In practice sectors with constant FODO cells are used
- Scaling ensures roughly constant fill factor
  - magnet strength (and length) is proportional to  $E/\beta \propto \sqrt(E)$
  - spacing is proportional to  $\beta \propto \sqrt(E)$
- Phase advance in cells is chosen as compromise of fill factor and stability with respect to ground motion
- Review will be needed
  - we might be able to reduce the focusing strength a bit
  - the phase advance optimum might have moved a bit

### Module Layout



- The articulation point and the quadrupoles can be moved
- Maybe need sheer point before quadrupole

### Lattice Design

- Preliminary lattice
  - quadrupoles need to be confirmed
  - some optimisations remain to be done
- Total length 20867.6mfill factor 78.6%
- 12 different sectors used
- Matching between sectors using 5 quadrupoles to allow for some energy bandwidth



## Beam Stability

- The beam is stable if the energy spread is large enough
  - at  $\Phi_2 = 8^\circ$  the stability is marginal
- Seems acceptable but cannot relax focusing very much
  - $\Rightarrow$  have to live with it



## Single Bunch Jitter Tolerances

- Assumed no correction
  - $\Rightarrow$  multi-pulse emittance is important
- $\bullet$  Value is given for  $0.1\,\mathrm{nm}$  emittance growth
  - quadrupole position:  $0.8\,\mathrm{nm}$
  - structure position:  $0.7\,\mu m$
  - structure angle:  $0.55 \,\mu$ radian
- $\Rightarrow$  Tolerances are very tight
  - in particular for quadrupole

### Different Error Contributions

- The main linac can be treated as a linear system
- For the same beam-based alignment method
  - $\Rightarrow$  emittance growth scales as the square of the errors
  - $\Rightarrow$  emittance growth for different errors can be calculated seperately (in most cases)
- But the choice of weights for DFS affects the results
  - large BPM position error pushes towards large weights
  - bad BPM resolution pushes towards small weights
  - $\Rightarrow$  compromise
  - $\Rightarrow$  cannot specify a tolerance easily, depends on other errors

## Error Sources

- Most important are
  - BPM position errors
  - BPM resolution
  - structure to beam misalignment
- BPM position errors and resolution determine the final dispersion left in the beam
- Structure offsets determine the final wakefield effect in the beam
  - if the wakefields are identical in two consecutive structures, the mean offsets is important
  - if wakefields are different, scattering of structures around mean value matters
    - should not matter for short-range wakefields
    - could matter for long-range wakefields

## Beam-Based Correction Strategy

- Make beam pass linac
  - one-to-one correction
- Remove dispersion
  - dispersion free steering
  - ballistic alignment
- Remove wakefield effects
  - accelerating structure alignment
  - emittance tuning bumps
- Tune luminosity
  - tuning knobs
- currently noise during correction is only taken into account in simplified way (e.g. beam jitter)

## Simulation Procedure and Benchmarking

- All simulation studies are performed with PLACET
  - based on 100 different machines
- Benchmarking of tracking codes is essential
- Comparisons performed in ILC framework
  - tracking with errors
  - alignment methods



### Misalignment Model: Module



- Sensors connect beam line to reference system
- Excellent prealignment of elements on the girders

### Misalignment Model: Flow Diagram



## Misalignment Model: Simplified Version

- In PLACET consider Three types of misalignment
  - articulation point (cradle)
  - articulation point to girder
  - girder to structure centre
- Error of reference line may contain systematics



## Accelerating Structure Alignment

#### PRE-ALIGNMENT

Ref.	1	Inherent accuracy of reference	10 µm	1σ
Ref. to	2	Sensor accuracy and electronics (reading error, noise,)	5 μm	<b>1</b> σ
cradle	3	Link sensor/cradle (supporting plates, interchangeability)	5 µm	<b>1</b> σ
Cradle to girder	4	Link cradle/girder	5 μm	1σ
Girder to AS	5a 5b	Link girder/acc. structure Inherent precision of structure	5 µm	<b>1</b> σ
		TOTAL	14 µm	1σ
		Tolerance	40 µm	3σ

**BEAM-BASED ALIGNMENT** 

6) relative position of structure and BPM reading

5μm 1σ

# Quadrupole Alignment

#### PRE-ALIGNMENT

Ref.	1	Inherent accuracy of reference	10 µm	1σ
Ref. to cradle	2	Sensor accuracy and electronics (reading error, noise,)	5 µm	1σ
	3	Link sensor/cradle (supporting plates, interchangeability)	5 µm	1σ
Cradle to Q	7a	Link cradle/quadrupole	5 µm	1σ
	7b	Inherent precision of quadrupole	10 µm	1σ
		TOTAL	17 µm	<b>1</b> σ
		Tolerance	50 µm	3σ

## **BPM** Alignment

#### PRE-ALIGNMENT

Ref.	1	Inherent accuracy of reference	10 µm	1σ
Ref. to cradle	2	Sensor accuracy and electronics (reading error, noise,)	<mark>5 μm</mark>	1σ
	3	Link sensor/cradle (supporting plates, interchangeability)	5 μm	1σ
Cradle to BPM	8a	Link cradle/quadrupole BPM axis	5 µm	1σ
BPM	8b	Inherent precision of quadrupole BPM axis	5 µm	1σ
	-	TOTAL	14 µm	1σ
		Tolerance	40 µm	3σ

#### BEAM-BASED ALIGNMENT:

8c) relative position of quadrupole and BPM reading

10 µm

1σ

# Assumed Alignment Performance

Element	error	with respect to	alignment		
			NLC	CLIC	
Structure	offset	girder	$25\mu\mathrm{m}$	$7\mu{ m m}$	
Structure	tilts	girder	$33\mu$ radian	?(cost)	
Girder	offset	survey line	$50\mu{ m m}$	$9.4(6.2)\mu\mathrm{m}$	
Girder	tilt	survey line	$15\mu$ radian	$9.4(6.2)\mu$ radian	
Quadrupole	offset	survey line	$50\mu{ m m}$	$17(13)\mu\mathrm{m}$	
BPM	offset	quadrupole/survey line	$100\mu{ m m}$	$14\mu{ m m}$	
BPM	resolution	BPM center	$0.3\mu{ m m}$	$0.1\mu{ m m}$	
Structure bpm	resolution	wake center	$5\mu{ m m}$	$5\mu{ m m}$	

### **One-To-One Correction**

• The beam is made to pass through the centres of the BPMs

 $\Rightarrow$  The result is very far from the target



## Tolerances

Element	error	with respect to	tolerance	
			CLIC	NLC
Structure	offset	beam	$4.3(5.8)\mu{ m m}$	$5.0\mu\mathrm{m}$
Structure	tilt	beam	$220\mu$ radian	$135\mu$ radian
Quadrupole	offset	straight line		—
Quadrupole	offset jitter	straight line	$13\mathrm{nm}$	—
Quadrupole	roll	axis	$240(240)\mu{ m m}$	$280\mu$ radian
BPM	offset	straight line	$0.4(0.44)\mu{ m m}$	$1.3\mu{ m m}$
BPM	resolution	BPM center	$0.4(0.44)\mu{ m m}$	$1.3\mu{ m m}$
Art. point	offset	straight line	$1.7(3)\mu\mathrm{m}$	
End point	offset	Art. point	$2.0(3.8)\mu{ m m}$	

- All tolerances are given after one-to-one steering, except quadrupole jitter
- In brackets low charge version

## Ballistic Alignment

- Beamline is divided into bins (12 quadrupoles)
- Quadrupoles in a bin are switched off
- Beam is steered into last BPM of bin
- BPMs are realigned to beam
- Quadrupoles are switched on
- Few-to-few steering is used



### Results for Ballistic Alignment

- The result is not satisfactory
- But much better compared to one-to-one
- Previous results showed that the earth magnetic field already has an influence



### **Dispersion Free Correction**

- Basic idea: use different beam energies
- NLC: switch on/off different accelerating structures
- CLIC (ILC): accelerate beams with different gradient and initial energy
- Optimise trajectories for different energies together:

$$S = \sum_{i=1}^{n} \left( w_i(x_{i,1})^2 + \sum_{j=2}^{m} w_{i,j}(x_{i,1} - x_{i,j})^2 \right) + \sum_{k=1}^{l} w'_k(c_k)^2$$

- Last term can be omitted
- Idea is to mimic energy differences that exist in the bunch with different beams

Alignment of Beginning of Main Linac



# DFS Results

- Optimum combination of  $w_1$  and  $w_2$  found
- Average emittance growth about is not acceptable





## Structure Alignment

- Each structure is equipped with a BPM (RMS position error  $5\,\mu m$ )
- Up to eight structures are mounted on movable girders
- $\Rightarrow$  Align structures to the beam
  - In the current simulation each structure is moved independently
  - A study had been performed to move the articulation points (N. Leros, D.S.)
    - $\Rightarrow$  small effect if chain is continuous
    - $\Rightarrow$  negligible additional effect if additional articulation point exists at quadrupoles
- $\Rightarrow$  Would like to revisit the problem to get rid of sheer point at quadrupoles

### Result for Ballistic Alignment

- Structure alignment is very efficient
  - large misalignments between BPMs and structures existed
  - they are removed by structure alignment
- $\Rightarrow$  The performance is almost satisfactory



# DFS Results



# DFS Results

- ⇒ With RF alignment we can have more then 90% of the machines below 5nm
- $\Rightarrow$  But not much margin



## Tuning Bumps

• Tuning bumps will be used to reduce the wakefield effects the beam accumulates wakefield kicks as

$$F(z) = w_{\perp}(z) \sum_{i=1}^{n} A_i y_i$$

the bump is used to zero the sum

$$F'(z) = w_{\perp}(z) \left( \sum_{i=1}^{n} A_i y_i + A_j \Delta y_j \right)$$

Residual remains

- energy spread in the beam (slight *z*-dependence of A)
- imperfect measurement/correction
- Bumps are simulated by moving a single structure transversely
  - previous studies showed that this is a good enough model (P. Eliasson, D.S.)

## Results for DFS

- Bumps are efficient
- Already a single bump (two degrees of freedom) is satisfactory
  - but we would use 3 or 5
- ⇒ Need to optimise taking into account convergence
  - Final average emittance in nm (bumps): 1.6 (0), 0.9 (1), 0.3 (3), 0.18 (5), 0.13 (7)



Dependence on Weigths (Old Parameters)

- For TRC parameters set
- One test beam is used with a different gradient and a different incoming beam energy
- $\Rightarrow$  BPM position errors are less important at large  $w_1$
- $\Rightarrow$  BPM resolution is less important at small  $w_1$
- $\Rightarrow$  Need to find a compromise
- $\Rightarrow$  Cannot give "the" tolerance for one error source



### New Parameters

- For new parameters similar dependence is found (as expected)
- can achieve
  - $\Delta \epsilon_y \approx 0.05 0.3 \,\mathrm{nm}$ for BPM misalignments
  - $\Delta \epsilon_y \approx 0.3-0.05 \,\mathrm{nm}$ for BPM resolution



## Long Distance Alignment

- In most simulations elements are scattered around a straight line
- In reality, the relative misalignments of different elements depends on their distance
- To be able to simulate this, PLACET can read misalignments from a file
  - simulation of pre-alignment is required
- To illustrate long-wavelength misalignments, simulations have been performed
  - cosine like misalignment used

Results 1



tolerance for  $\Delta \epsilon_y$ =1nm [µm]

### Results 2





Results 3



tolerance for  $\Delta \epsilon_y$ =1nm [µm]

## Long-Range Wake Fields

- Wake-fields are know in time or frequency domain
- Time domain is time consuming:

$$F_n = e \sum_{i=1}^n W_{\perp}(z_n - z_i)(x_i q_i)$$

 $\Rightarrow$  use FFT (convolution theorem)

 $\Rightarrow$  or mode model (in linacs often sufficient):

$$W_{\perp}(z) = \sum_{j=0}^{n} a_j \sin\left(\frac{2\pi z}{\lambda_j}\right) \exp\left(-\frac{\pi z}{\lambda_j Q_j}\right)$$

can be evaluated very efficiently

# **CLIC** Longrange Wakefields

- Long-range wakefields are important
- Simulation of emittance growth due to beam jit-ter
  - no energy spread (pessimistic)
- Allowed wake at second bunch is  $\approx 4.5 \, \mathrm{kV/pCm^2}$

 $\Rightarrow$  seems acceptable



### Static Effects

- If all structures have the same long-range wake, the tuning bumps are curing short- and long-range effects at the same time
  - $\Rightarrow$  simulations indicate small additional effects in other lattices
- For different longrange wakes the compensation is not guaranteed
  - $\Rightarrow$  need to develop a model for long-range wakes with errors
- Wakefield tolerance given is for the wake envelope
  - $\Rightarrow$  spread is wakes should lead to lower average kick
- We could develop special long-range bumps e.g. based on train straightener

## Conclusion

- New lattice design is waiting for confirmation of quadrupole lengths
  - final optimisation will be performed once this is done
- Performance corresponds to expected values from scaling
- A model for the alignment has been developed in the module working group
  - needs continuation
  - a complex data transfer between alignment and beam dyanmics is required
- Static tuning study needs to be repeated (in more complete version) for final lattice
- Dynamic effects and feedback need to be included
- Multi-bunch effects need to be treated
- For a number of these studies the strategy is know and needs to be applied
  - in some cases more development remains to be done